

**AMENDMENTS TO THE CLAIMS**

1. (Canceled)
2. (Currently Amended) The noise controller of claim ~~6~~ 7, further comprising:  
a signal amplifying part amplifying said noise signal from said sensor part;  
a first low pass filter filtering said amplified noise signal from said signal amplifying part and outputting a filtered noise signal to said phase perceiving part and said micro computer part;  
a second low pass filter filtering said noise control signal from said micro computer part;  
an electric power amplifying part amplifying a filtered noise control signal from said second low pass filter; and  
an output part outputting an amplified filtered noise control signal from said electric power amplifying part.
3. (Currently Amended) The noise controller of claim ~~6~~ 7, wherein said micro computer includes an index table.
4. (Currently Amended) The noise controller of claim ~~6~~ 7, wherein said micro computer includes a neural net.

5. (Currently Amended) The noise controller of claim ~~6~~ 7, wherein said micro computer includes a control rule controlling part (CRCP) generating said noise control signal to minimize said residual noise signal.

6. (Canceled)

7. (Previously Presented) A noise controller for actively controlling noise, the controller comprising:

a sensor part perceiving a noise and outputting a noise signal corresponding to said noise;

a phase perceiving part perceiving a phase of said noise signal and outputting a phase signal, said phase perceiving part including a transformer transforming said noise signal, a full-wave rectifier rectifying a transformed noise signal from said transformer, a pressure-sensitive circuit converting a fully rectified signal from said full-wave rectifier, and a bandpass filter bandpass filtering a converted signal from said pressure-sensitive circuit; and

a micro computer part generating a noise control signal based on a residual noise signal and an error variation signal.

8-10. (Canceled)

11. (Currently Amended) The method of claim ~~15~~ 16, further comprising:

amplifying said noise signal;

low pass filtering said amplified noise signal;  
low pass filtering said noise control signal;  
power amplifying said filtered noise control signal; and  
outputting said power amplified filtered noise control signal.

**12.** (Canceled)

**13.** (Currently Amended) The method of claim **15** **16**, wherein said residual noise signal and said error variation signal are generated through the use of a neural net.

**14.** (Currently Amended) The method of claim **15** **16**, wherein said noise control signal is generated to minimize said residual noise signal.

**15.** (Canceled)

**16.** (Previously Presented) A method of actively controlling noise, the method comprising:

perceiving a noise and generating a noise signal;  
perceiving a phase of said noise signal and generating a phase signal, said phase perceiving step comprising transforming said noise signal, full-wave rectifying said transformed noise signal, converting said fully rectified signal, and bandpass filtering said converted signal; and

generating a noise control signal based on a residual noise signal and an error variation signal.

**17-18.** (Canceled)